

#### ITS World Congress

Bordeaux, France 5 to 9 October 2015

## Role of evaluation research when moving from lab to production

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#### TOWARDS INTELLIGENT MOBILITY Better use of space



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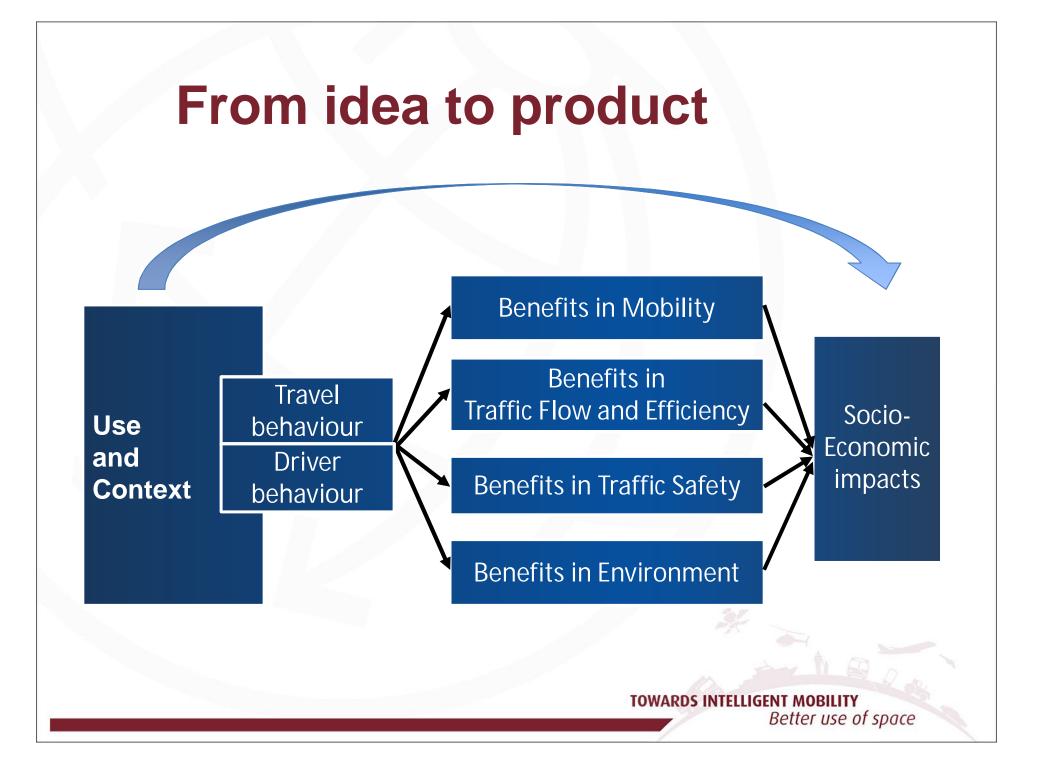
## Content

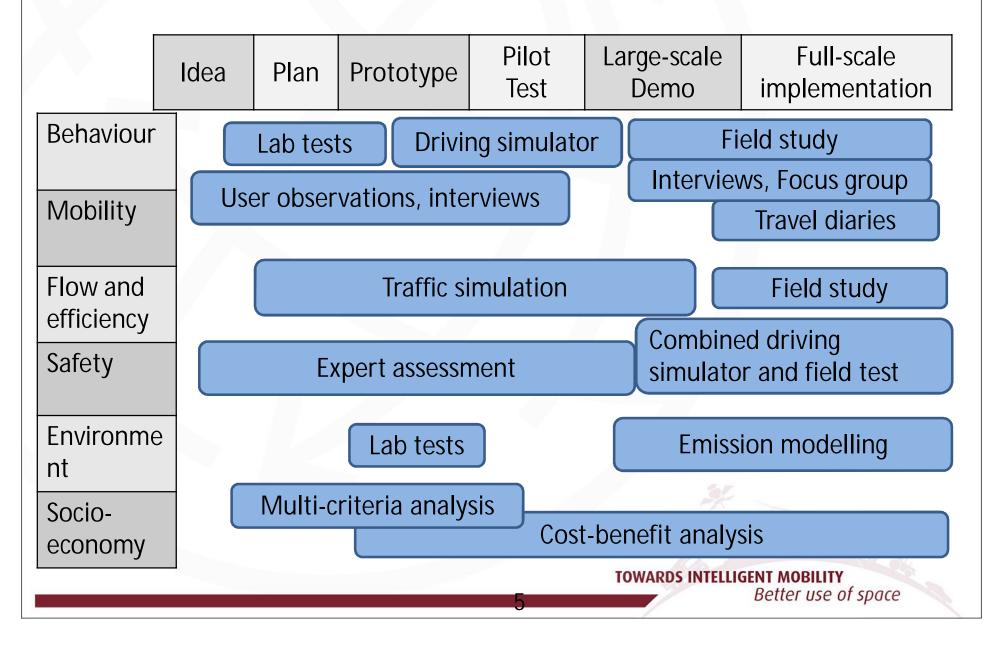
- 1. Evaluation methods in life cycle of a service
- 2. Developing applications in TEAM "Tomorrows' Elastic Adaptive Mobility"
- 3. Role of evaluation / TEAM apps
  - 1. Parking
  - 2. Collaborative ACC
- 4. Conclusions

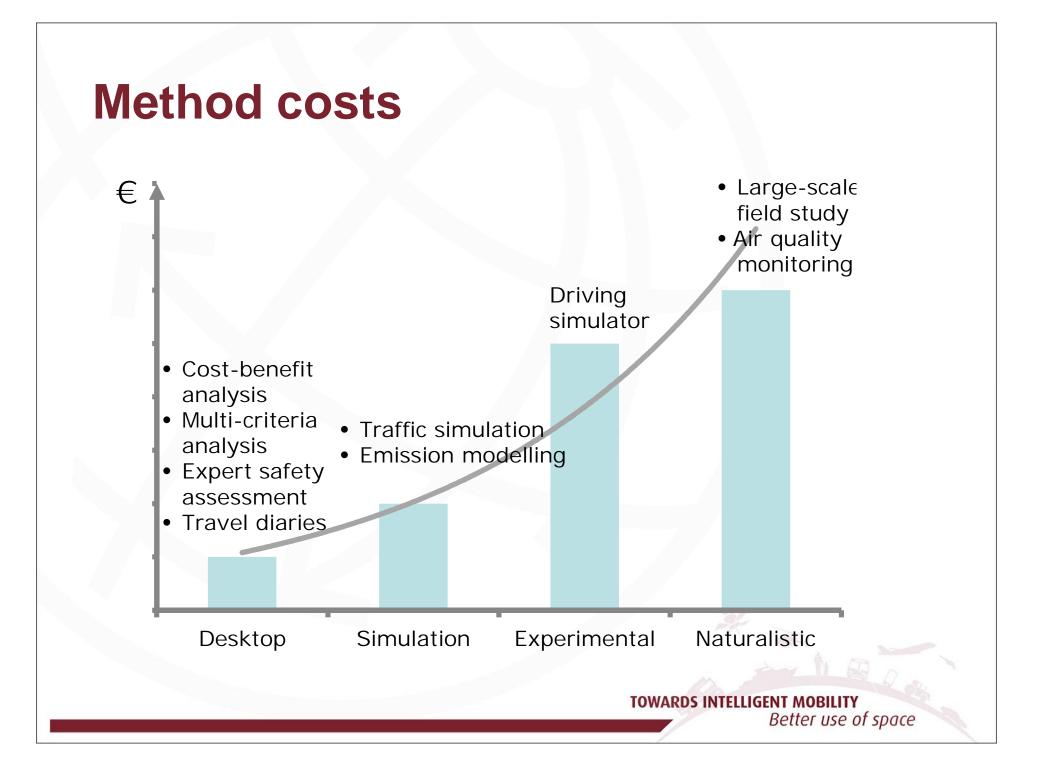


iCars Network

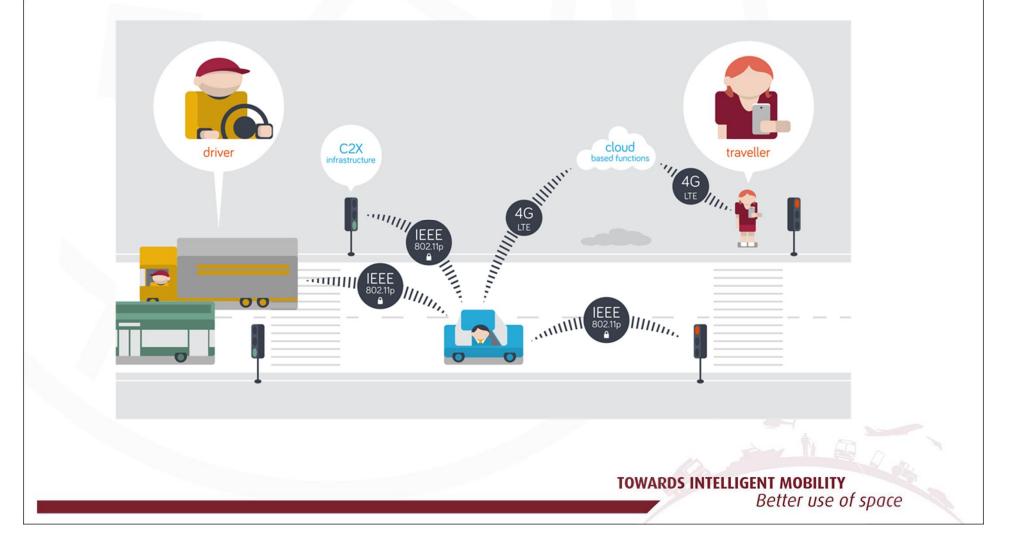
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# **TEAM vision: drivers and travelers are integrated to collaborative transport**



## **TEAM** applications

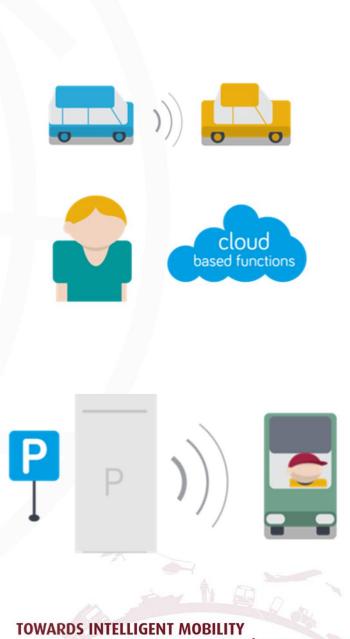
- 1. Collaborative pro-active urban/inter-urban monitoring and adhoc control
- 2. Collaborative co-modal route planning
- 3. Co-modal coaching with support from virtual/avatar users
- 4. Collaborative smart intersections for intelligent priorities
- 5. Collaborative public transport optimization
- 6. Collaborative dynamic corridors
- 7. Collaborative adaptive cruise control
- 8. Collaborative eco-friendly parking
- 9. Collaborative driving and merging
- 10. Green, safe and collaborative driving serious game and community building

Better use of space

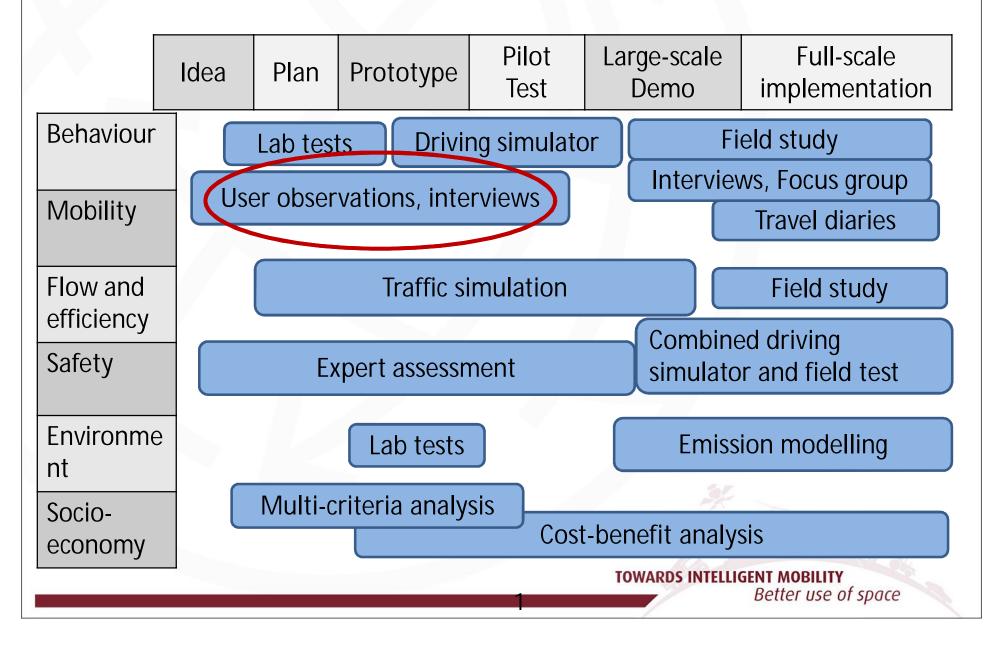
11. Collaborative eco-friendly navigation

## **Short descriptions**

- 1. Collaborative adaptive cruise control
- Wireless communication V2V and V2I in order to harmonize cruising speed
- Traffic information (incidents, traffic lights, VMS) and user centric information into account
- Improved safety and efficiency
- 2. Collaborative eco-friendly parking
- Real time information about free parking spaces
- Parking/leaving detection (press a button/automatic)
- Cloud based monitoring about availability
- On street and P-house



Better use of space

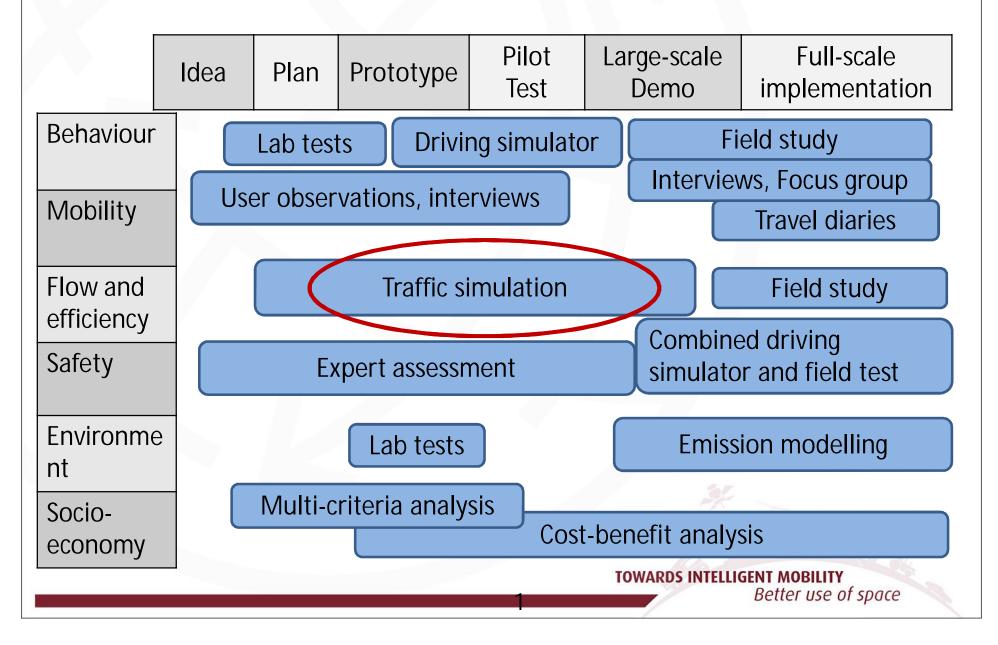


## **Real users in real life**

In early phase, understanding user needs, definition of user *demand* and user *benefits* 

Different types of users in *transport system*: Travellers -> Companies -> Operators -> Authorities,

- 1. Collaborative adaptive cruise control
  - Drivers benefit with an extended foresight range that can better predict density to improve traffic flow
  - Towards automated driving and better management of traffic flow
- 2. Collaborative eco-friendly parking
  - Drivers can quickly detect optimal parking conditions while cities can allocate parking space more efficiently
  - Traffic management

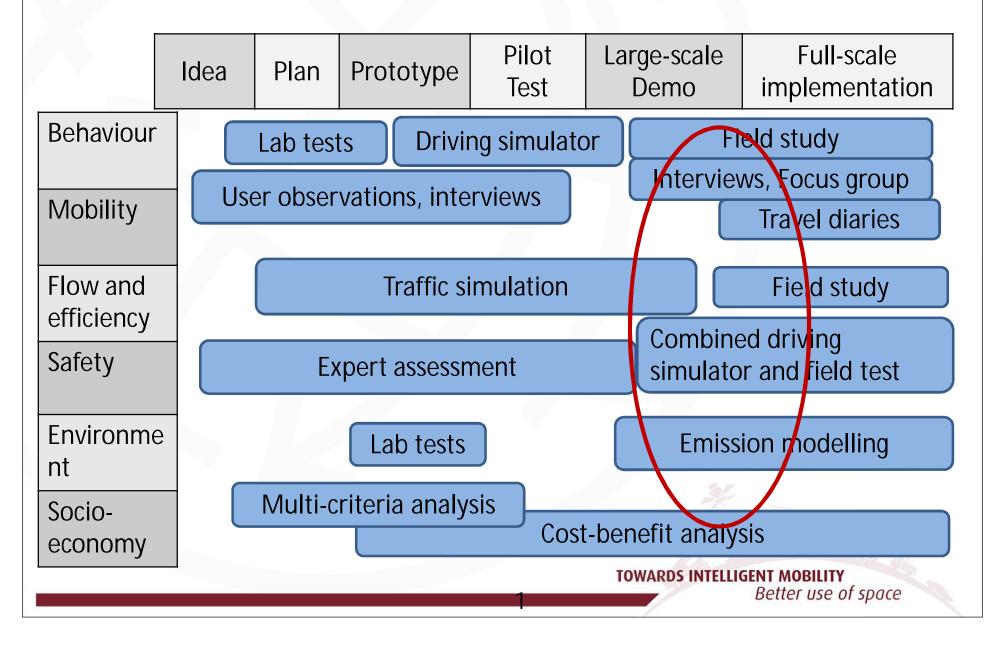


## **Traffic simulations**

Input for simulations from results of earlier studies, expert assessment and results from demos in field Adaptation of the simulation tools

- 1. Collaborative adaptive cruise control
  - Impacts in traffic flow when driver/vehicle receives information from vehicles upstream
- 2. Collaborative eco-friendly parking
  - Searching time for a parking place
  - Emissions in searching time
  - Car exposure in city centres

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# **Euro Eco Challenge in field**

Combination of approaches to get real user experience

- Demos citizens
- Test drives and passengers in the equipped cars

Technical testing in different locations

Combinations of data collection

- Interview data to assess
- Focus groups to provide new ideas and suggestions how to develop
- Observations to get insight on driver/user reactions
- Inputs and validation of modelling

Workshops to assess the role of Collaborative adaptive cruise control and Collaborative eco-friendly parking in *proactive traffic management* 

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## Conclusions

- Important to start evaluation from the very beginning identify the demand
- Organize evaluation activities for whole life cycle
- Consider costs and reasoning of evaluation activities
- Different approaches in evaluation to reach common users
- Recognize users in different level of the transport system get full benefit out of the system
- Provide evidence about impacts of the system up to cost benefit results
- Convince different stakeholders from consumers to road authorities